



# Porting Guide from Open AT<sup>®</sup> OS V2.10b to V3.10

Revision: 001  
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**wavocom**<sup>®</sup>  
Make it wireless

# Porting guide from Open AT<sup>®</sup> OS v2.10b to v3.10

Reference : **WM\_DEV\_OAT\_UGD\_022**

Version : **001**

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## **Overview**

This user guide describes the main differences between the Open AT<sup>®</sup> interfaces from version 2 generation to version 3 generation. For each modified interface, code samples are provided. New interfaces are also briefly described.

## Document History


<b>Level</b>	<b>Date</b>	<b>History of the evolution</b>	
001	11 <sup>th</sup> August, 2006	Creation	

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# **1 Introduction**

## **1.1 References**

- I. Open AT<sup>®</sup> Development Guide for revision 009  
(Ref WM\_ASW\_OAT\_UGD\_002 revision 009)

## 1.2 Glossary

<b>Application Mandatory API</b>	Mandatory software interfaces to be used by the Embedded Application.
<b>AT commands</b>	Set of standard modem commands.
<b>AT function</b>	Software that processes the AT commands and AT subscriptions.
<b>Embedded API layer</b>	Software developed by Wavecom, containing the Open AT <sup>®</sup> APIs (Application Mandatory API, AT Command Embedded API, OS API, Standard API, FCM API, IO API, and BUS API).
<b>Embedded Application</b>	User application sources to be compiled and run on a Wavecom product.
<b>Embedded Core software</b>	Software that includes the Embedded Application and the Wavecom library.
<b>Embedded software</b>	User application binary: set of Embedded Application sources + Wavecom library.
<b>External Application</b>	Application external to the Wavecom product that sends AT commands through the serial link.
<b>Target</b>	Open AT <sup>®</sup> compatible product supporting an Embedded Application.
<b>Target Monitoring Tool</b>	Set of utilities used to monitor a Wavecom product.
<b>Receive command pre-parsing</b>	Process for intercepting AT responses.
<b>Send command pre-parsing</b>	Process for intercepting AT commands.
<b>Standard API</b>	Standard set of "C" functions.
<b>Wavecom library</b>	Library delivered by Wavecom to interface Embedded Application sources with Wavecom Core Software functions.
<b>Wavecom Core Software</b>	Set of GSM and open functions supplied to the User.

### **1.3 Abbreviations**

<b>A&amp;D</b>	Application & Data
<b>ADL</b>	Application Development Layer
<b>API</b>	Application Programming Interface
<b>CPU</b>	Central Processing Unit
<b>IR</b>	Infrared
<b>KB</b>	Kilobyte
<b>OS</b>	Operating System
<b>PDU</b>	Protocol Data Unit
<b>RAM</b>	Random-Access Memory
<b>ROM</b>	Read-Only Memory
<b>RTK</b>	Real-Time Kernel
<b>SDK</b>	Software Development Kit
<b>SMA</b>	Small Adapter
<b>SMS</b>	Short Message Services
<b>WAP</b>	Wireless Application Protocol
<b>IDE</b>	Integrated Development Environment

## 2 Modified Basic Mode interfaces

This chapter lists all modified interfaces from v2.10b generation to v3.10, with code samples.

### 2.1 Minimum Embedded Application Code

The following minimum application code in Open AT<sup>®</sup> OS v3 must be added to write an Open AT<sup>®</sup> v3 application.

```
const wm_apmTask_t wm_apmTask [ WM_APM_MAX_TASK ] =
{
    { StackSize1, Stack1, InitFct1, ParseFct1 },
    { StackSize2, Stack2, InitFct2, ParseFct2 },
    { StackSize3, Stack3, InitFct3, ParseFct3 }
};
```

Here **Stackx** and **StackSizex** are variables used to define the application task call and stack size.

**InitFctx** are functions called during initialization. **ParseFctx** are functions which are called each time a message is received.

These functions have to be defined and implemented by the user.

### 2.2 Open AT<sup>®</sup> OS Specific AT Commands

#### 2.2.1 AT+WOPEN command

This command is used to start/stop/configure an Open AT<sup>®</sup> application.

From Open AT<sup>®</sup> OS v3.10, this command has been modified to configure the A&D and Open AT<sup>®</sup> application space. The new parameters available with this command are mentioned below:

Parameter	Description
5	Suspend the Open AT <sup>®</sup> embedded application tasks
6	If the A&D size parameter is used, configure the Application and storage size, otherwise display the current A&D storage space size and Open application space size

## 2.3 Memory Management

The Embedded software runs within an RTK task: the user must define the size of the customer application call stack. The Wavecom Core Software and the Embedded Application manage their own RAM area. Any access from one of these programs to the other's RAM area is prohibited and causes a reboot.

In case an Embedded Application uses more than the maximum allocated RAM in global variables, or uses more than the maximum allocated ROM, then the behavior of the embedded software becomes erratic. Global variables, call stack and dynamic memory are all part of the RAM allocated to the Embedded Application.

The memory configuration is different in Open AT® OS v3.10. The difference in memory configuration is mentioned below:

Old Memory Configuration
<p>For 16 Mbits flash size products:</p> <ul style="list-style-type: none"> <li>• 320 Kbytes of ROM</li> <li>• 32 Kbytes of RAM</li> <li>• 5 Kbytes of Flash Object Data</li> </ul> <p>For 32 Mbits flash size products:</p> <ul style="list-style-type: none"> <li>• 512 Kbytes of ROM</li> <li>• 128 Kbytes of RAM</li> <li>• 128 Kbytes of Flash Object Data</li> </ul>
New Memory configuration
<p>For 32 Mbits flash size products :</p> <ul style="list-style-type: none"> <li>• 768 Kbytes of ROM (configurable using AT+WOPEN command)</li> <li>• 128 Kbytes of RAM</li> <li>• 128 Kbytes of Flash Object Data</li> <li>• 768 Kbytes of Application and Data Storage Volume (configurable using AT+WOPEN command)</li> </ul> <p>Note: 16 Mbits product are not supported in this version</p>



## **2.4 Security**

### **2.4.1 Software Security**

Two software safeguards are used in the Open AT<sup>®</sup> platform:

- RAM access protection
- Watchdog protection

After reboot, the input parameter of "wm\_apmApplilnit ()" function is set to WM\_APM\_REBOOT\_FROM\_EXCEPTION. If a reboot is caused by a software crash, the application is started 20 seconds after the start of the Wavecom OS. This allows at least 20 seconds delay to re-download a new application. In case of normal reboot, the application restarts immediately.

### **2.4.2 WatchDog Protection**

The Embedded Application software is protected from reaching a dead-end lock by a watchdog timer value. In case of a crash, the software reboots. If an Embedded Application crash is detected, the Target Monitoring Tool screen displays: "Customer watchdog". The watchdog timer value has been changed in Open AT<sup>®</sup> OS v3.10 to 8 seconds from 4.2 seconds.

## 2.5 API

### 2.5.1 New Open AT<sup>®</sup> Tasks Configuration APIs

These APIs allows to configure the tasks parameters such as stack size. These APIs are added from Open AT<sup>®</sup> OS v3.10. This section describes the various parameters that needs to be configured for tasks.

#### 2.5.1.1 Task Identifiers

The tasks are identified by the task identifiers based on the following type

```
typedef enum
{
    WM_OS_TASK_1,           // Task 1
    WM_OS_TASK_2,           // Task 2
    WM_OS_TASK_3,           // Task 3
    WM_OS_TASK_MAX,        // Task number
    WM_OS_TASK_WAVECOM = 0xFF // For message coming from
                               //Wavecom Core
                               // Software
} wm_osTask_e;
```

#### 2.5.1.2 Task Table

The task table is used to define the embedded application tasks parameters

```
typedef struct
{
    u32 StackSize;           /* Stack Size */
    u32 *Stack;             /* Stack pointer */
    s32 (*Init) ( wm_apmInitType_e ); /* Initialisation function */
    s32 (*Parser) ( wm_apmMsg_t * ); /* Parser function */
} wm_apmTask_t;
```

The table has to be defined by the application as below :

```
const wm_apmTask_t wm_apmTask [ WM_APM_MAX_TASK ] =
{
    { StackSize1, Stack1, Init1, Parser1 },
    { StackSize2, Stack2, Init2, Parser2 },
    { StackSize3, Stack3, Init3, Parser3 }
};
```

**Note:** to use less than 3 tasks, the additional tasks parameters must be set to 0 in the table `wm_apmTask`.

### 2.5.1.3 Stack initialization

The following variables are used to define stack size for each task.

```
#define StackSize1 1024 // Value 1024 is a sample value
#define StackSize2 1024 // Value 1024 is a sample value
#define StackSize3 1024 // Value 1024 is a sample value

u32 Stack1 [ StackSize1 / 4 ];
u32 Stack2 [ StackSize2 / 4 ];
u32 Stack3 [ StackSize3 / 4 ];
```

These data represent the amount of memory needed by each task call stack.

### 2.5.1.4 The init functions

This function is called during initialization of the task.

Prototype:

```
s32 Init ( wm_apmInitType_e InitType )
```

### 2.5.1.5 The Parser functions

These functions are invoked, each time a message is received from the Wavecom core software.

Prototype:

```
s32 Parser( wm_apmMsg_t * Message );
```

New message structures and message types are added to the body of `wm_apmMsg_t` (shown in **bold**). The structures of these messages are explained below. The message body is as follows

```
/* Body Part of the Message */
typedef union
{
    wm_atResponse_t           ATResponse;
    wm_atUnsolicited_t      ATUnsolicited;
    wm_atIntermediate_t    ATIntermediate;
    wm_atCmdPreParser_t     ATCmdPreParser;
    wm_atRspPreParser_t     ATRspPreParser;
    wm_osTimer_t           OSTimer;
    wm_osRelease_t         OSRelease;
}
```

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```
wm_fcmReceiveBlock_t      FCMReceiveBlock;  
wm_fcmOpenFlow_t         FCMOpenFlow;  
wm_fcmFlow_e             FCMCloseFlow;  
wm_fcmFlow_e             FCMResumeFlow;  
wm_ioSerialSwitchStateRsp_t IOSerialSwitchStateRsp;  
wm_ioPortUpdateInfo_t    IOPortUpdateInfo;  
} wm_apmBody_t
```

WM\_IO\_PORT\_UPDATE\_INFO:

```
typedef struct  
{  
    wm_ioPort_e      Port; // Port identifier  
    wm_ioPortUpdateType_e Update; // Update type (Opened/Closed)  
} wm_ioPortUpdateInfo_t;
```

The wm\_ioPortUpdateType\_e type is described below:

```
typedef enum  
{  
    WM_IO_PORT_UPDATE_OPENED, // New opened port  
    WM_IO_PORT_UPDATE_CLOSED  // The port is now closed  
} wm_ioPortUpdateType_e;
```

## 2.6 AT Command API's

These API's are used to manage the AT commands. This includes

- sending of AT command string
- reception of AT responses
- pre-parsing of at commands and at responses
- intermediate at responses
- unsolicited responses

### 2.6.1 The `wm_atSendCommand` function (*Unchanged*)

Prototype:

```
void wm_atSendCommand ( u16 AtStringSize, wm_atSendRspType_e  
                        ResponseType, ascii *AtString );
```

This function is a shortcut to the `wm_atSendCommandExt` function, with the `Dest` parameter always set to the `WM_IO_OPEN_AT_VIRTUAL_BASE` value.

### 2.6.2 The `wm_atSendCommandExt` Function (*New*)

The `wm_atSendCommand` function allows sending AT commands on a required port.

Prototype:

```
void wm_atSendCommandExt ( u16 AtStringSize, wm_atSendRspType_e  
                           ResponseType, ascii *AtString, wm_ioPort_e Dest );
```

Parameters:

- **AtString:** Any AT command string in ASCII character (terminated by a 0x00). Several strings can be sent at the same time, depending on the type of ATcommand.
- **AtStringSize:** Size of the previous parameter, It equals the length + 1 and includes the 0x00 character.
- **ResponseType:** Determines whether the response will be sent to external and/or embedded application This parameter can take the values defined in the below mentioned enumeration.:

```
typedef enum  
{  
    WM_AT_SEND_RSP_TO_EMBEDDED,  
    /* Default value */  
    WM_AT_SEND_RSP_TO_EXTERNAL,
```

```
WM_AT_SEND_RSP_BROADCAST
} wm_atSendRspType_e;
```

WM\_AT\_SEND\_RSP\_TO\_EMBEDDED means that all the AT responses will be sent back to the Embedded Application (default mode).

WM\_AT\_SEND\_RSP\_TO\_EXTERNAL means that all the AT responses will be sent back to the External Application (PC).

WM\_AT\_SEND\_RSP\_BROADCAST means that all the AT responses will be broadcasted to both the Embedded and External Applications (PC).

- **Dest:** Specifies the port on which the AT commands has to be executed.

### **2.6.3 The `wm_atUnsolicitedSubscription` function (*Unchanged*)**

Prototype:

```
void wm_atUnsolicitedSubscription(wm_atUnsolicited_e Unsolicited);
```

The function subscribes to the unsolicited messages. The unsolicited messages include incoming call indication, WIND indications, etc.

### **2.6.4 The `wm_atIntermediateSubscription` function (*Unchanged*)**

Prototype:

```
void wm_atIntermediateSubscription(wm_atIntermediate_e Intermediate);
```

The function subscribes to the intermediate messages. The intermediate messages include responses like ">".

### **2.6.5 The `wm_atCmdPreParserSubscribe` function (*Unchanged*)**

Prototype:

```
void wm_atCmdPreParserSubscribe (wm_atCmdPreSubscribe_e
SubscribeType);
```

The function subscribes to the Command Pre Parsing of AT Command String.

### **2.6.6 The `wm_atRspPreParserSubscribe` function (*Unchanged*)**

Prototype:

```
void wm_atRspPreParserSubscribe (wm_atRspPreSubscribe_e
SubscribeType);
```

The function subscribes to the Response Pre Parsing of AT Command String.

### 2.6.7 The `wm_atSendRspExternalApp` function (*Unchanged*)

Prototype:

```
void wm_atSendRspExternalApp ( u16 AtStringSize, ascii *AtString );
```

This function sends an AT response to the external application. This function is a shortcut to `wm_atSendRspExternalAppExt` function but the destination is always UART1.

### 2.6.8 The `wm_atSendRspExternalAppExt` function (*New*)

Prototype:

```
void wm_atSendRspExternalAppExt ( u16 AtStringSize, ascii *AtString,  
wm_ioPort_e Dest );
```

Parameters:

- **AtStringSize:** Any AT command string in ASCII character (terminated by a 0x00). Several strings can be sent at the same time, depending on the type of ATcommand.
- **AtStringSize:** Size of the previous parameter, It equals the length + 1 and includes the 0x00 character
- **Dest:** Specifies the port where the specified responses have to be sent. Available ports may be opened and closed dynamically by any application (an external or an Open AT<sup>®</sup> one)

### 2.6.9 The `wm_atSendUnsolicitedExternalApp` function (*Unchanged*)

The `wm_atSendUnsolicitedExternalApp` function sends an AT unsolicited response to the External Application. The Unsolicited response will be sent to all ports.

Prototype:

```
void wm_atSendUnsolicitedExternalApp ( u16 AtStringSize, ascii  
*AtString );
```

### 2.6.10 The `wm_atSendUnsolicitedExternalAppExt` function (*New*)

This function behaves similar to the `wm_atSendUnsolicitedExternalApp` function, It provides an additional parameter to send the unsolicited response on one specific port, instead of broadcasting it on all ports.

Prototype:

```
void wm_atSendUnsolicitedExternalApp ( u16 AtStringSize, ascii  
*AtString , wm_ioPort_e Dest);
```

Parameters:

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- **AtStringSize:** Any AT command string in ASCII character (terminated by a 0x00). Several strings can be sent at the same time, depending on the type of ATcommand.
- **AtStringSize:** Size of the previous parameter, It equals the length + 1 and includes the 0x00 character
- **Dest:** Specifies the port where the specified responses have to be sent. Available ports may be opened and closed dynamically by any application (an external or an Open AT<sup>®</sup> one).

### **2.6.11 The `wm_atSendIntermediateExternalApp` function (Unchanged)**

This function sends an AT intermediate response to the external application (always on UART1).

Prototype:

```
void wm_atSendIntermediateExternalApp ( u16 AtStringSize, ascii  
                                         *AtString );
```

### **2.6.12 The `wm_atSendIntermediateExternalAppExt` function (New)**

This function sends an intermediate AT response to the external application. The sender can decide the port on which the response should be sent

Prototype:

```
void wm_atSendIntermediateExternalAppExt ( u16 AtStringSize, ascii  
                                         *AtString, wm_ioPort_e Dest );
```

.Parameters:

- **AtStringSize:** Any AT command string in ASCII character (terminated by a 0x00). Several strings can be sent at the same time, depending on the type of ATcommand.
- **AtStringSize:** Size of the previous parameter, It equals the length + 1 and includes the 0x00 character
- **Dest:** Specifies the port where the specified responses have to be sent. Available ports may be opened and closed dynamically by any application (an external or an Open AT<sup>®</sup> one).



## 2.7 Debug API's

### 2.7.1 The **wm\_osDebugTrace** Function (*Unchanged*)

Prototype:

```
s32 wm_osDebugTrace ( u8 Level, const ascii *Format, ... );
```

Debug function to print the debug information.

### 2.7.2 The **wm\_osDebugFatalError** Function (*Unchanged*)

Prototype:

```
s32 wm_osDebugFatalError ( const ascii * ErrorFormat);
```

This stores the error code and performs a reboot.

### 2.7.3 The **wm\_osDebugEraseAllBackTraces** Function (*New*)

Prototype:

```
void wm_osDebugEraseAllBackTraces ( void )
```

This function reinitializes the product backtraces storage space. All the currently stored backtraces are erased.

### 2.7.4 The **wm\_osDebugInitBacktracesAnalysis** Function (*New*)

Prototype:

```
s32 wm_osDebugInitBacktracesAnalysis ( void );
```

This function has to be called in order to start the debug analysis.

### 2.7.5 The **wm\_osDebugRetrieveBacktrace** Function (*New*)

Prototype:

```
s32 wm_osDebugRetrieveBacktrace ( u8 * BacktraceBuffer, u16 Size );
```

This function retrieves the next stored backtrace in the product's memory. Before the first call to this function, the **wm\_osDebugInitBacktracesAnalysis** function has to be called in order to initialize the analysis. Successive calls to the function will allow to retrieve all the **wm\_osDebugRetrieveBacktrace** backtraces, until the function returns a negative value.

## 2.8 OS API's

These APIs manage the timer and the flash. The return value of OS API's is 'OK' on success and 'ERROR' on error.

### 2.8.1 The **wm\_osStartTimer** function (*Unchanged*)

Prototype:

```
s32 wm_osStartTimer ( u8 TimerId, bool bCyclic, u32 TimerValue );
```

Starts the timer defined by timer Id

### 2.8.2 The **wm\_osStopTimer** function (*Unchanged*)

Prototype:

```
s32 wm_osStopTimer ( u8 TimerId );
```

Stops the timer identified by timer Id

### 2.8.3 The **wm\_osStartTickTimer** function (*New*)

Prototype:

```
s32 wm_osStartTickTimer ( u8 TimerId, bool bCyclic, u32 TimerValue );
```

Starts the timer identified by timer Id. The 'TimerValue' is in steps of 18.5 ms ticks.

### 2.8.4 The **wm\_osStopTickTimer** function (*New*)

Prototype:

```
s32 wm_osStopTickTimer ( u8 TimerId );
```

Stops the timer identified by 'TimerId' and started by **wm\_osStartTickTimer**().

#### **Note on Flash Management**

Flash identifiers up to 2000 can exist at the same time using Open AT<sup>®</sup> OS v3.10. Valid values are 0 to 0xFFFF

### 2.8.5 The **wm\_osWriteFlashData** function (*Unchanged*)

Prototype:

```
s32 wm_osWriteFlashData (u16 Id, u16 DataLen, u8 * Data );
```

Writes data in the flash memory and the Id is assigned to the stored data,

**2.8.6 The wm\_osReadFlashData function (Unchanged)**

Prototype:

s32 wm\_osReadFlashData (u16 Id, u16 DataLen, u8 \*Data );

Reads the data from the flash referred by Id.

**2.8.7 The wm\_osGetLenFlashData function (Unchanged)**

Prototype:

s32 wm\_osGetLenFlashData (u16 Id );

Gives the length of the data stored in flash memory referred by Id

**2.8.8 The wm\_osDeleteFlashData function (Unchanged)**

Prototype:

s32 wm\_osDeleteFlashData (u16 Id );

Deletes the Data stored in flash memory referred by Id

**2.8.9 The wm\_osDeleteAllFlashData function (Unchanged)**

Prototype:

s32 wm\_osDeleteAllFlashData (void);

Deletes all the Data stored in flash memory

**2.8.10 The wm\_osGetAllowedMemoryFlashData function (Changed)**

Prototype:

s32 wm\_osGetAllowedMemoryFlashData ( void );

Get the allowed flash memory

Old interface
<pre>//Get allocated memory wm_osGetAllocatedMemoryFlashData( );</pre>
New interface
<pre>...  // Get allocated memory wm_osGetAllowedMemoryFlashData( );</pre>

**2.8.11 The `wm_osGetFreeMemoryFlashData` function (*Unchanged*)**

Prototype:

```
s32 wm_osGetFreeMemoryFlashData ( void );
```

Get the free flash memory.

**2.8.12 The `wm_osGetUsedMemoryFlashData` Function (*New*)**

Prototype:

```
s32 wm_osGetUsedMemoryFlashData ( u16 StartId, u16 EndId );
```

The `wm_osGetUsedMemoryFlashData` function returns the quantity of memory used by flash objects between the provided start & end IDs.

**2.8.13 The `wm_osDeleteAllFlashData` Function (*New*)**

Prototype:

```
s32 wm_osDeleteAllFlashData ( void );
```

The `wm_osDeleteAllFlashData` function deletes all the data previously stored in flash memory by the Embedded Application.

**2.8.14 The `wm_osDeleteRangeFlashData` Function (*New*)**

Prototype:

```
s32 wm_osDeleteRangeFlashData ( u16 StartId, u16 EndId );
```

The `wm_osDeleteRangeFlashData` function deletes all the flash objects between the provided start & end IDs.

**2.8.15 The wm\_osGetHeapMemory function (Unchanged)**

Prototype:

```
void * wm_osGetHeapMemory ( u16 MemorySize );
```

Allocate dynamic memory (in bytes).

**2.8.16 The wm\_osReleaseHeapMemory function (Unchanged)**

Prototype:

```
s32 wm_osReleaseHeapMemory ( void * ptrData );
```

Releases the previously allocated heap memory.

**2.8.17 The wm\_osSuspend function (New)**

Prototype:

```
void wm_osSuspend( void);
```

Suspends all OAT tasks in the kernel; the tasks will not be run by the scheduler.

**2.8.18 The wm\_osGetTask function (New)**

Prototype:

```
u8 wm_osGetTask ( void );
```

Get the current task Id.

**2.8.19 The wm\_osSendMsg function (New)**

Prototype:

```
s8 wm_osSendMsg ( wm_osTask_e Task, u8 MsgID, u16 MsgLength, u8 *  
MsgBody );
```

Sends a message to required task.

## 2.9 FCM Service

The flow control manager API's provide two I/O flows to the embedded application, one from V24 and other from a data communication. In Open-AT v3, the data communication is possible through GPRS along with GSM.

V24 serial link has following flows since OAT v3.10

- UART1
- UART2
- USB
- Logical CMUX flows
- Logical Bluetooth flows

### 2.9.1 Required Header

In the FCM header file, the **wm\_fcmFlow\_e** enum type maps to enum **wm\_ioPort\_e** which has additional entries since OAT v3 (Shown in bold). This corresponds to the added flows.

```
typedef enum
{
    WM_IO_NO_PORT,
    WM_IO_UART1,    // Uart 1 port
    WM_IO_UART2,    // Uart 2 port
#ifdef __WAVECOM_DEC__
    WM_IO_USB,      // USB port

    WM_IO_UART_MAX = WM_IO_USB,    // Number of physical Uarts
#else
    WM_IO_UART_MAX,
#endif // __WAVECOM_DEC__
    WM_IO_UART1_VIRTUAL_BASE    = 0x10, // Base for UART1 virtual
ports
    WM_IO_UART2_VIRTUAL_BASE    = 0x20, // Base for UART2 virtual
ports
    WM_IO_USB_VIRTUAL_BASE      = 0x30, // Base for USB virtual ports
}
```

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```
WM_IO_BLUETOOTH_VIRTUAL_BASE    = 0x40, // Base for BlueTooth
virtual ports
WM_IO_GSM_BASE                  = 0x50, // Base for GSM CSD FCM data
flow
WM_IO_GPRS_BASE                 = 0x60, // Base for GPRS FCM Data flow
WM_IO_OPEN_AT_VIRTUAL_BASE      = 0x80 // Base for Open-AT
application tasks
} wm_ioPort_e;
```

### **2.9.2 Functions Removed**

- wm\_fcmOpenGPRSAndV24
- wm\_fcmCloseGPRSAndV24
- wm\_fcmOpenDataAndV24
- wm\_fcmCloseDataAndV24

### **2.9.3 The wm\_fcmlsAvailable Function (New)**

Prototype:

```
bool wm_fcmlsAvailable ( wm_fcmFlow_e FlowID );
```

This function allows to check if the required port is available and ready to handle the FCM service.

### **2.9.4 The wm\_fcmOpen function (New)**

Prototype:

```
s32 wm_fcmOpen ( wm_fcmFlow_e Flow, u16 DataMaxToReceive );
```

Opens the requested flow with specified maximum packet size. The packet size should not exceed 120 for serial link, 270 for GSM data flow and is not used for GPRS flow.

### **2.9.5 The wm\_fcmClose function (New)**

Prototype:

```
s32 wm_fcmClose ( wm_fcmFlow_e Flow );
```

Closes the requested flow.

### **2.9.6 The `wm_fcmSubmitData` function (*Unchanged*)**

Prototype:

```
s32 wm_fcmSubmitData ( wm_fcmFlow_e Flow, wm_fcmSendBlock_t*  
fcmDataBlock );
```

The embedded application uses this function to submit data to FCM

The value returned by the function is as per the defined return values.

### **2.9.7 The `wm_fcmCreditToRelease` function (*Unchanged*)**

Prototype:

```
s32 wm_fcmCreditToRelease ( wm_fcmFlow_e Flow, u8 Credits );
```

This function tells the flow control manager that the customer has already used the data received in one or several messages.

The value returned by the function is as per the defined return values.

### **2.9.8 The `wm_fcmQuery` function (*New*)**

Prototype:

```
s32 wm_fcmQuery (wm_fcmFlow_e Flow, wm_fcmWay_e Way);
```

The function gives the status of the FCM buffers.



## 2.10 Input Output API

These APIs manage serial link state and GPIO operations.

- The members in the union **wm\_ioLabel\_u** have been modified. The new member is specified in bold.

```
/* GPIO labels union */
typedef union
{
    wm_ioLabel_Q24X0_e    Q24X0_Label; /*GPIO labels Q24X0 Product */
    wm_ioLabel_Q24X3_e    Q24X3_Label; /* GPIO labels Q24X3 Product */
    wm_ioLabel_Q24X6_e    Q24X6_Label; /* GPIO labels Q24X6 Product */
    wm_ioLabel_P32X3_e    P32X3_Label; /* GPIO labels P3XX3 Product */
    wm_ioLabel_P32X6_e    P32X6_Label; /* GPIO labels P32X6 Product */
    wm_ioLabel_Q31X6_e    Q31X6_Label; /* GPIO labels Q31X6 Product */
    wm_ioLabel_P51X6_e    P51X6_Label; /* GPIO labels P5186 Product */
    wm_ioLabel_P25X1_e    P25X1_Label; /* GPIO labels Q2501 Product */
} wm_ioLabel_u;
```

- Following ENUMs have been added

```
/* GPIO labels for Wismo Quick P2501 product */
typedef enum
{
    WM_IO_Q25X1_GPI        = 0x00000001,
    WM_IO_Q25X1_GPO_0     = 0x00000002,
    WM_IO_Q25X1_GPO_1     = 0x00000004,
    WM_IO_Q25X1_GPO_2     = 0x00000008,
    WM_IO_Q25X1_GPO_3     = 0x00000010,
    WM_IO_Q25X1_GPIO_0    = 0x00000020,
    WM_IO_Q25X1_GPIO_1    = 0x00000040,
    WM_IO_Q25X1_GPIO_2    = 0x00000080,
    WM_IO_Q25X1_GPIO_3    = 0x00000100,
    WM_IO_Q25X1_GPIO_4    = 0x00000200,
    WM_IO_Q25X1_GPIO_5    = 0x00000400,
    WM_IO_P51X6_PAD       = 0x7FFFFFFF
} wm_ioLabel_P25X1_e;
```

### 2.10.1 The **wm\_ioSerialSwitchState** function (*Changed*)

Prototype:

```
void wm_ioSerialSwitchState ( wm_ioPort_e Port,
                             wm_ioSerialSwitchState_e SerialState );
```

Sets the mode of the requested serial interface

- The `wm_ioPort_e` has following values

```
typedef enum
{
    WM_IO_UART1,    // Uart 1 port
    WM_IO_UART2,    // Uart 2 port
    WM_IO_USB,      // USB port

    WM_IO_UART1_VIRTUAL_BASE = 0x10,
    WM_IO_UART2_VIRTUAL_BASE = 0x20,
    WM_IO_USB_VIRTUAL_BASE   = 0x30,
    WM_IO_BLUETOOTH_VIRTUAL_BASE = 0x40,
    WM_IO_GSM_BASE = 0x50,
    WM_IO_GPRS_BASE = 0x60,
    WM_IO_OPEN_AT_VIRTUAL_BASE = 0x80
} wm_ioPort_e;
```

Old interface
<pre>// Switch back to AT mode wm_ioSerialSwitchState ( WM_IO_SERIAL_AT_MODE );</pre>
New interface
<pre>// Switch back to AT mode wm_ioSerialSwitchState ( WM_IO_UART1, WM_IO_SERIAL_AT_MODE );</pre>

### 2.10.2 The `wm_ioSerialGetSignal` function *(New)*

Prototype:

```
s32 wm_ioSerialGetSignal( wm_ioPort_e Port, wm_ioSerialGetSignal_e
                          SerialSignal);
```

Get the current value of a signal.

### 2.10.3 The `wmiolsPortAvailable` function *(New)*

Prototype:

```
bool wmiolsPortAvailable ( wm_ioPort_e Port );
```

The function allows to query the current port state (open or closed).

#### **2.10.4 The `wm_ioAllocate` function (*Unchanged*)**

Prototype:

```
s32 wm_ioAllocate ( u32 NbGpioToAllocate, wm_ioConfig_t *  
                  GpioCustomerConfig );
```

This function is used to reserve the GPIO(s) for Open AT<sup>®</sup> application.

#### **2.10.5 The `wm_ioRelease` function (*Unchanged*)**

Prototype:

```
s32 wm_ioRelease ( s32 Handle, u32 NbGpioToRelease, wm_ioLabel_u *  
                  GpioCustomerLabel );
```

Releases one or more GPIO(s) reserved by the application.

#### **2.10.6 The `wm_ioSetDirection` function (*Unchanged*)**

Prototype:

```
s32 wm_ioSetDirection ( s32 Handle, u32 NbGpioToGhangeDir,  
                        wm_ioSetDirection_t * GpioDirection );
```

This function changes one or more GPIO(s) direction.

#### **2.10.7 The `wm_ioRead` function (*Unchanged*)**

Prototype:

```
s32 wm_ioRead ( s32 Handle, u32 Gpio, u32 * GpioState );
```

Reads one or more GPIO(s) state.

#### **2.10.8 The `wm_ioSingleRead` function (*Unchanged*)**

Prototype:

```
s32 wm_ioSingleRead ( s32 Handle, u32 Gpio );
```

Reads one GPIO state.

#### **2.10.9 The `wm_ioWrite` function (*Unchanged*)**

Prototype:

```
s32 wm_ioWrite ( s32 Handle, u32 Gpio, u32 GpioState );
```

Writes one or more GPIO(s) state.

**2.10.10 The `wm_ioSingleWrite` function (*Unchanged*)**

Prototype:

```
s32 wm_ioSingleWrite ( s32 Handle, u32 Gpio, u32 State );
```

This function writes one GPIO state.

## **2.11 GPRS Service (*Unchanged*)**

This service allows management of GPRS connectivity through the Wavecom modem. The API's available are as follows

**wm\_gprsAuthentication:** Allows setting the authentication parameters login/password to use with a context id during PDP activation

**wm\_gprsIPCPInformations:** Allows getting the current IPCP information to use with a particular context id after PDP activation.

**wm\_gprsOpen:** Allows setting OpenAT as the user of the GPRS bearer associated with the context id.

**wm\_gprsClose:** Allows to unset OpenAT as the user of the GPRS bearer associated with the context id

## **2.12 List API (*Unchanged*)**

None

## 2.13 BUS Service

For bus operations the Q2501 Wireless CPU behaves as a Q2406B wireless CPU.

### 2.13.1 The `wm_busOpen` function (*Unchanged*)

Prototype :

```
s32 wm_busOpen ( u32 BusType, u32 Mode, wm_busSettings_u *  
Settings );
```

- The new member of the `chipselct` has following defined constant  
`WM_BUS_SPI_ADDRESS_CS_NONE` – The chipselect is not handled by the Open AT<sup>®</sup> API, but will be handled inside the Open AT<sup>®</sup> application.

### 2.13.2 The `wm_busClose` function (*Unchanged*)

Prototype :

```
s32 wm_busClose ( s32 Handle );
```

This function allows to close a previously opened bus.

### 2.13.3 The `wm_busWrite` function (*Unchanged*)

Prototype:

```
s32 wm_busWrite ( s32 Handle, wm_busAccess_t * pAccessMode, void *  
pDataToWrite, u32 NbBytes );
```

Allows to write data on previously allocated bus. The second parameter "address" has been changed o "pAccessMode".

### 2.13.4 The `wm_busRead` function (*Unchanged*)

Prototype:

```
s32 wm_busRead ( s32 Handle, wm_busAccess_t * pAccessMode, void *  
pDataToRead, u32 NbBytes );
```

This function allows to read data from a previously allocated bus.

## **2.14 LIST Management (*Unchanged*)**

These APIs provide the management of LIST data structure.

- wm\_IstCreate** : Creates the list
- wm\_IstDestroy** : Allows to clear and destroy the list
- wm\_IstClear** : Allows to clear all provided list items without destroying
- wm\_IstGetCount** : Returns the current item count
- wm\_IstAddItem** : Allows to add an item to the provided list
- wm\_IstInsertItem** : Allows to add an item at a given location in list
- wm\_IstDeleteItem** : Allows to delete an item at the given indexes in list
- wm\_IstFindItem** : Allows to find an item in the provided list
- wm\_IstFindAllItem** : Allows to find all items in the provided list
- wm\_IstFindNextItem** : Allows to find the next item index of the given list
- wm\_IstResetItem** : Allows to reset all previously found items by  
**wm\_IstFindNextItem()**.



## **2.15 Standard Library Functions (*Unchanged*)**

None

## **3 Deprecated Basic Mode Features**

### **3.1 Scratch Memory APIs**

The Scratch memory API does no more exist from Open AT<sup>®</sup> OS v3.10. In order to implement Over the Air Download, the Application and Data Storage API has to be used. All the scratch memory functions will return WM\_SCRATCH\_MEMORY\_NOT\_AVAIL error code.

The Application and Data storage APIs can be found in the section 4.

## 4 New Basic Mode Features

### 4.1 Application and Data Storage API

#### 4.1.1 The **wm\_adAllocate** function (*New*)

Prototype :

```
s32 wm_adAllocate ( u32 CellID, u32 Size, wm_adHandle_t * Handle );
```

Allocates a new cell in the Application and data storage API.

#### 4.1.2 The **wm\_adWrite** function (*New*)

Prototype :

```
s32 wm_adWrite ( wm_adHandle_t * Handle, u32 Size, void * Data );
```

Writes data to the requested cell.

#### 4.1.3 The **wm\_adInfo** function (*New*)

Prototype :

```
s32 wm_adInfo ( wm_adHandle_t * Handle, wm_adInfo_t * Info );
```

Obtains information on requested cell handle.

#### 4.1.4 The **wm\_adFinalise** function (*New*)

Prototype :

```
s32 wm_adFinalise ( wm_adHandle_t * Handle );
```

Finalizes a cell; this one will be then in read-only mode.

#### **4.1.5 The wm\_adInstall function (New)**

Prototype :

```
s32 wm_adInstall ( wm_adHandle_t * Handle );
```

Installs the provided A&D cell content.

#### **4.1.6 Other A&D APIs**

The A&D service also provides these APIs :

<b>wm_adRetrieve</b>	: Initialize a handle on an already allocated cell
<b>wm_adFindInit</b>	: Initialize a cell search
<b>wm_adFindNext</b>	: Get next cell handle from initialized search
<b>wm_adResume</b> non finalized cell	: Allow to resume write operations on the requested
<b>wm_adDelete</b>	: Delete the requested cell.
<b>wm_adStats</b> storage space	: Provide information on the Application & Data
<b>wm_adSpaceState</b>	: Return the Application & Data storage space state
<b>wm_adFormat</b> space	: Destroy the whole Application & Data storage
<b>wm_adRecompactInit</b>	: Start the recompactation process
<b>wm_adRecompact</b>	: Perform a new recompactation step

## 4.2 Sound API

### 4.2.1 The **wm\_sndTonePlay** function (*New*)

Prototype:

```
s32 wm_sndTonePlay ( wm_snd_dest_e Destination, u16 Frequency, u8  
Duration, u8 Gain );
```

Plays a tone.

### 4.2.2 The **wm\_sndToneStop** function (*New*)

Prototype:

```
s32 wm_sndToneStop ( wm_snd_dest_e Destination );
```

Stops a tone.

### 4.2.3 The **wm\_sndDtmfPlay** function (*New*)

Prototype:

```
s32 wm_sndDtmfPlay ( wm_snd_dest_e Destination, ascii Dtmf, u8  
Duration, u8 Gain );
```

Plays a dtmf tone.

### 4.2.4 The **wm\_sndDtmfStop** function (*New*)

Prototype:

```
s32 wm_sndDtmfStop ( wm_snd_dest_e Destination );
```

Stops a dtmf tone.

### 4.2.5 The **wm\_sndMelodyPlay** function (*New*)

Prototype:

```
s32 wm_sndMelodyPlay ( wm_snd_dest_e Destination, u16* Melody, u16  
Tempo, u8 Cycle, u8 Gain );
```

Plays a melody.

#### **4.2.6 The `wm_sndMelodyStop` function (*New*)**

Prototype:

```
s32 wm_sndMelodyStop ( wm_snd_dest_e Destination );
```

Stops a melody.

### **4.3 GPS API**

This service provides APIs to access the Q2501 product GPS data.

## **4.4 RTC API**

This service provides APIs to access the Real Time Clock in the wireless CPU directly.



## **5 Modified ADL Interfaces**

### **5.1 Imported API's from Standard Mode**

The following APIs are added in Open AT® OS v3.10 from the standard mode.

- |                    |                                       |
|--------------------|---------------------------------------|
| Standard API       | - Imported in both the versions       |
| List API           | - Imported in both the versions       |
| Scratch Memory API | - Imported only in Open AT® OS v2.10b |
| Sound APIs         | - Imported only in Open AT® OS v3.10  |

## **5.2 UART2 and GPIOs shared resources**

When the second UART of the product is used some of the GPIOs are no more available to the Open AT<sup>®</sup> application. The impacted GPIOs are mentioned below:

<b>Wavecom Module Series</b>	<b>Unavailable GPIOs</b>
Q24X6	GPI, GPO 2, GPIO 0, GPIO 5
Q24X0	GPI, GPO 2, GPIO 0, GPIO 5
Q2501	GPI, GPO 2, GPIO 0, GPIO 5
Q32X6	GPI, GPIO 2
Q31X6	GPI, GPO 2, GPIO 4, GPIO 5
Q51X6	GPO 0, GPO 1, GPIO 5

### **5.3 Q2501 product external battery mechanism**

On the Q2501 product, if the external battery charging mechanism is implemented (please refer to the AT+WHCNF command documentation), the Open AT<sup>®</sup> applications. GPIO 3 is locked on start-up, and is not available for Open AT<sup>®</sup>.

## **5.4 SIM Level Shifter and GPO shared resources**

If any other feature than the "SIM3VONLY" one is enabled (please refer to the AT+WFM command documentation), a GPO (according to the table below, depending on the module) is locked for the SIM level shifter, and cannot be subscribed by the Open AT<sup>®</sup> application.

<b>Wavecom Module Series</b>	<b>Unavailable GPO</b>
Q24X6	GPO 0
Q24X0	GPO 0
Q25X1	GPO 1

## 5.5 Inner AT commands configuration

The ADL library needs for its internal processes to set-up some AT command configurations that differ from the default values. The concerned commands are listed below:

AT Command	Fixed Value
AT+CMEE 1	1
AT+WIND	All indications
AT+CREG	2
AT+CGREG	2
AT+CRC	1
AT+CGEREP	2
ATV	1
ATQ	0

The above fixed values are set-up internally by ADL. This means that all related error codes (for +CMEE) or unsolicited results are always all available to all ADL applications, without requiring them to be sent (using the AT corresponding configuration command).

## 5.6 AT Command Services

These API's are used to manage the AT commands. This includes

- sending of AT command string
- reception of AT responses
- pre-parsing of at commands and at responses
- intermediate at responses
- unsolicited responses

Due to the new UART support, AT commands related APIs have been modified to process multi-UART settings.

### 5.6.1 Unsolicited and Subscribed commands structure

The `adl_atCmdPreParser_t` structure (used when a subscribed command is received) includes a new "**Port**" field, which is set to the UART id from which the command has been entered.

```
typedef struct
{
    u16      Type;           // Cmd type
    u8       NbPara;        // Parameters number
    adl_atPort_e Port;     // Source port
    wm_lst_t ParaList;      // Parameters list
    u16      StrLength;     // Command string length
    ascii    StrData[1];    // Command string
} adl_atCmdPreParser_t;
```

The `adl_atUnsolicited_t` structure includes a new "**Dest**" field to get the destination port.

```
typedef struct
{
    adl_strID_e RspID; // Standard response ID
    adl_atPort_e Dest; // Unsolicited response destination port
    u16 StrLength;
    /* the length of the string (name) of the unsolicited response */
    ascii StrData[1];
    /* a pointer to the string (name) of the unsolicited response */
} adl_atUnsolicited_t;
```

### 5.6.2 The `adl_atUnSoSubscribe` function (*Unchanged*)

Prototype:

```
s16 adl_atUnSoSubscribe (ascii * UnSostr, adl_atUnSoHandler_t UnSohdl);
```

This function subscribes to a specific unsolicited response with an associated callback function. When the required unsolicited response is sent from the Wavecom Core Software, the callback function will be executed.

### 5.6.3 The `adl_atUnSoUnSubscribe` function (*Unchanged*)

Prototype:

```
s16 adl_atUnSoUnSubscribe ( ascii *UnSostr, adl_atUnSoHandler_t  
UnSohdl );
```

This function un-subscribes from an unsolicited response and its handler.

### 5.6.4 `adl_atSendResponse` APIs (*Changed*)

Prototypes:

```
void adl_atSendResponse ( u16 Type, ascii * Text );
```

```
void adl_atSendStdResponse ( u16 Type, adl_strID_e RspID );
```

```
void adl_atSendStdResponseExt ( u16 Type, adl_strID_e RspID, u32 arg );
```

The Type parameter of these APIs may now be set using the following macro :

```
ADL_AT_PORT_TYPE ( port, type )
```

where port is the destination port where to send the response, and type is the response type (ADL\_AT\_RSP, ADL\_AT\_INT or ADL\_AT\_UN).

Unsolicited responses are broadcasted to all ports. By default, if this macro is not used, responses are sent to the UART 1.

Old interface
<pre>// Command Handler void CmdHdl (adl_atCmdPreParser_t * cmd) {     // Reply OK     adl_atSendStdResponse (         ADL_AT_RSP,         ADL_STR_OK ); } </pre>
New interface
<pre>// Command Handler void CmdHdl (adl_atCmdPreParser_t * cmd) {     // Reply OK on incoming UART     adl_atSendStdResponse ( ADL_AT_PORT_TYPE (ADL_AT_RSP,cmd-&gt;Port) ,         ADL_STR_OK ); } </pre>

### 5.6.5 Additional macros for specific port access

The above Response sending functions may be also used with the macros below, which provide the additional Port argument : it should avoid heavy code including each time the ADL\_AT\_PORT\_TYPE macro call.

```
#define adl_atSendResponsePort(_t,_p,_r)
adl_atSendResponse(ADL_AT_PORT_TYPE(_p,_t),_r)

#define adl_atSendStdResponsePort(_t,_p,_r)
adl_atSendStdResponse(ADL_AT_PORT_TYPE(_p,_t),_r)

#define adl_atSendStdResponseExtPort(_t,_p,_r,_a)
adl_atSendStdResponseExt(ADL_AT_PORT_TYPE(_p,_t),_r,_a)

```

### 5.6.6 The adl\_atCmdCreate function (*Changed*)

Prototype :

```
void adl_atCmdCreate ( ascii *atstr, u16 rspflag, adl_atRspHandler_t
    rsphdl, ... );
```

The "rspflag" parameter of this API may now be set using the following macro:

```
ADL_AT_PORT_TYPE ( port, type )
```

where port is the destination port where to send unsubscribed responses, and type is a Boolean value (TRUE to forward unsubscribed responses, FALSE to filter them).

By default, if this macro is not used, responses are sent to the UART 1.



### 5.6.7 The `adl_atCmdSendText` function (New)

Prototype:

`s8 adl_atCmdSendText ( adl_port_e Port, ascii * Text )`

This API is used to send intermediate text for a command which requires intermediate input text (For e.g. AT+CMGS).

#### Parameters

- **Port:** Port on which is currently running the "Text Mode" command, waiting for some text input.
- **Text:** Text to be provided to the running "Text Mode" command on the required port. If the text does not end with a 'Ctrl-Z' character (0x1A code), the function will add it automatically.

#### **Returned values:**

OK on success and negative values on error.

## **5.7 Timer Services**

In the new Open AT<sup>®</sup> OS version 32 timers can run at the same time. There are no changes in the API interfaces for the timer.

## **5.8 Memory Services**

A new API is added in this service to check the type of the memory.

### **5.8.1 The `adl_memGetType` function (New)**

Prototype:

**The `adl_memType_e adl_memGetType (void);`**

The function returns the current module memory type. The `adl_memType_e` enumerated list is explained below:

```
typedef enum
{
    ADL_MEM_TYPE_A,
    ADL_MEM_TYPE_B
} adl_memType_e;
```

## **5.9 Debug Services**

When the Full Debug configuration is selected in the used IDE (or with the command), the `__DEBUG_APP__` and `__DEBUG_FULL__` compilation flags are both defined and also the following macros. The macros defined in bold are the new ones.

TRACE (( u8 TL, ascii \* T, ... ))

DUMP ( u8 TL, u8 \* P, u16 L )

**FULL\_TRACE** (( u8 TL, ascii \* T, ... )) //Works exactly as the TRACE macro.

**FULL\_DUMP** ( u8 TL, u8 \* P, u16 L ) //Works exactly as the DUMP macro.

## 5.10 Flash service

In ADL v3.10 generation, flash objects' IDs are related to a provided handle, subscribed before any flash service API call.

### 5.10.1 The `adl_flhSubscribe` function (*New*)

Prototype:

```
s8 adl_flhSubscribe ( ascii * Handle, u16 NbObjectsRes );
```

Subscribes to a flash handle, and links a finished objects number to it.

### 5.10.2 The `adl_flhExist` function (*Changed*)

Prototype:

```
s32 adl_flhExist( ascii * Handle, u16 ID );
```

Gets the length of the requested flash object. May return a negative value on error.

Old interface
<pre>// Retrieve the length u16 TheLength = adl_flhExist ( THE_ID ); // Test the length if ( TheLength ) {     // The object exists }</pre>
New interface
<pre>// Retrieve the length s32 TheLength = adl_flhExist ( MyFlhHandle, THE_ID ); // Test the length if ( TheLength &gt; OK ) {     // The object exists }</pre>

### 5.10.3 The `adl_flhRead` function *(Changed)*

Prototype:

```
s8 adl_flhRead( ascii * Handle, u16 ID, u16 Len, u8 * ReadData );
```

Reads data from the requested object.

Old interface
<pre>// Reads the object data u8 pData [ 10 ]; s8 sRet = adl_flhRead ( THE_ID, 10, pData );</pre>
New interface
<pre>// Reads the object data u8 pData [ 10 ]; s8 sRet = adl_flhRead ( MyFlhHandle, THE_ID, 10, pData );</pre>

### 5.10.4 The `adl_flhWrite` function *(Changed)*

Prototype:

```
s8 adl_flhWrite( ascii * Handle, u16 ID, u16 Len, u8 * WriteData );
```

Writes data in the requested object.

Old interface
<pre>// Write the object data u8 pData [ 10 ]; s8 sRet = adl_flhWrite ( THE_ID, 10, pData );</pre>
New interface
<pre>// Write the object data u8 pData [ 10 ]; s8 sRet = adl_flhWrite ( MyFlhHandle, THE_ID, 10, pData );</pre>

### 5.10.5 The `adl_flhErase` function (*Changed*)

Prototype:

```
s8 adl_flhErase( ascii * Handle, u16 ID );
```

Erases requested object.

Old interface
// Erase the object s8 sRet = adl_flhErase ( THE_ID );
New interface
// Erase the object s8 sRet = adl_flhErase ( MyFlhHandle, THE_ID );

### 5.10.6 The `adl_flhGetFreeMem` function (*Unchanged*)

Prototype:

```
u32 adl_flhGetFreeMem( void );
```

Gets currently free flash memory.

### 5.10.7 The `adl_flhGetIDCount` function (*New*)

Prototype:

```
s32 adl_flhGetIDCount( ascii * Handle );
```

Gets the provided handle ID count, or the remaining ID count, if the parameter is set to NULL.

### **5.10.8 The adl\_flhGetUsedSize function (*New*)**

Prototype:

```
s32 adl_flhGetUsedSize( ascii * Handle, u16 StartID, u16 EndID );
```

Gets the used size by an ID range in the handle.



## 5.11 FCM service

Due to new UART support, FCM constants have been modified to process multi-UART settings.

### Flow IDs

The different flow IDs are now defined by the following enum

```

/* Ports identifiers */
typedef enum
{
    ADL_PORT_NONE,

    ADL_PORT_UART1,
    ADL_PORT_UART2,
    ADL_PORT_USB,

    ADL_PORT_MAX = ADL_PORT_USB,

    ADL_PORT_UART1_VIRTUAL_BASE    = 0x10, // Base for UART1
virtual ports
    ADL_PORT_UART2_VIRTUAL_BASE    = 0x20, // Base for UART2
virtual ports
    ADL_PORT_USB_VIRTUAL_BASE      = 0x30, // Base for USB virtual
ports
    ADL_PORT_BLUETOOTH_VIRTUAL_BASE = 0x40, // Base for
BlueTooth virtual ports
    ADL_PORT_GSM_BASE              = 0x50, // GSM CSD call data port
    ADL_PORT_GPRS_BASE             = 0x60, // GPRS session port
    ADL_PORT_OPEN_AT_VIRTUAL_BASE  = 0x80 // Base for Open-AT
application tasks
} adl_port_e;

```

All flows may be subscribed in slave mode, with a bit-wise OR with following constant

```

// Flow subscribed as slave only
#define ADL_FCM_FLOW_SLAVE 0x20

```

To keep compatibility with v2 generation, old IDs are also redefined

```

// Constants for compatibility
#define ADL_FCM_FLOW_V24_MASTER ADL_FCM_FLOW_V24_UART1
#define ADL_FCM_FLOW_V24        ( ADL_FCM_FLOW_V24_UART1 |
ADL_FCM_FLOW_SLAVE )

/* GPRS preferred on V24 Master subscription */

```

**August 11<sup>th</sup>, 2006**

// Constant kept for compatibility ; not used anymore  
#define ADL\_FCM\_FLOW\_GPRS\_PREFERRED 0x80

Old interface
<pre>// Subscribe to V24 flow s8 FcmHdl = adl_fcmSubscribe ( ADL_FCM_FLOW_V24_MASTER, MyFcmCtrlHandler, MyFcmDataHandler );</pre>
New interface
<pre>// Subscribe to V24 flow s8 FcmHdl = adl_fcmSubscribe ( ADL_FCM_FLOW_V24_UART1, MyFcmCtrlHandler, MyFcmDataHandler );</pre>

## **5.12 Scratch Memory API**

This API has been replaced by the Application & Data Storage service. Please refer to this [New Features in ADL](#) description for a porting sample.

### **5.13 GPIO Service (*Unchanged*)**

There are no changes in the API for the GPIO service. Please find below the GPIOs for the new Q2501 product.

For Wismo Quik Q25X1 product:

- ADL\_IO\_Q25X1\_GPI
- ADL\_IO\_Q25X1\_GPO\_0
- ADL\_IO\_Q25X1\_GPO\_1
- ADL\_IO\_Q25X1\_GPO\_2
- ADL\_IO\_Q25X1\_GPO\_3
- ADL\_IO\_Q25X1\_GPIO\_0
- ADL\_IO\_Q25X1\_GPIO\_1
- ADL\_IO\_Q25X1\_GPIO\_2
- ADL\_IO\_Q25X1\_GPIO\_3
- ADL\_IO\_Q25X1\_GPIO\_4
- ADL\_IO\_Q25X1\_GPIO\_5

### **5.14 Bus Service (*Unchanged*)**

The new member of the Chip Select has following defined constant **ADL\_BUS\_SPI\_ADDRESS\_CS\_NONE** - The chipselect is not handled by the Open AT<sup>®</sup> API, but will be handled inside the Open AT<sup>®</sup> application.

## **5.15 Errors Management**

This feature contains the APIs for error management.

### **5.15.1 The `adl_errHalt` function (New)**

Prototype:

```
void adl_errHalt ( u16 ErrorID const ascii *ErrorString );
```

This function causes an error, defined by its ID and string. If an error handler is defined, it will be called, otherwise a product reset will occur.

### **5.15.2 The `adl_errEraseAllBacktraces` function (New)**

Prototype:

```
void adl_errEraseAllBacktraces ( void );
```

Backtraces (caused by the `adl_errHalt` function, ADL or the Wavecom Core Software) are stored in the product non-volatile memory. A limited number of backtraces may be stored in memory (depending on each backtrace size, and other internal parameters stored in the same storage place). The function allows to free and re-initialize this storage place.

### **5.15.3 The `adl_errStartBacktraceAnalysis` function (New)**

Prototype:

```
void adl_errStartBacktraceAnalysis (void);
```

This function is to start the analysis to retrieve the backtraces from the memory.

### **5.15.4 The `adl_errGetAnalysisState` function (New)**

Prototype:

```
adl_errAnalysisState_e adl_errGetAnalysisState ( void );
```

This function is used to know the current backtrace analysis process state.

### **5.15.5 The `adl_errRetrieveNextBacktrace` function (New)**

Prototype:

```
s32 adl_errRetrieveNextBacktrace ( u8 Handle , u8 * BacktraceBuffer, u16  
Size );
```

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This function allows the application to retrieve the next backtrace buffer stored in the product memory. The backtrace analysis may have been started first with the function *adl\_errGetAnalysisState*.

## **5.16 SIM Service**

### **5.16.1 The `adl_simGetState` function (*New*)**

Prototype

```
adl_simState_e adl_simGetState ( void );
```

This function gets the current SIM service state.



## 5.17 Call Service

### 5.17.1 The `adl_callSetup` function (*Unchanged*)

This function calls the `adl_callSetupExt` function on `ADL_PORT_OPEN_AT_VIRTUAL_BASE` port. Please note that events generated by the `adl_callSetup` will not be able to be forwarded to any external port, since the setup command was running on the Open AT<sup>®</sup> OS.

### 5.17.2 The `adl_callSetupExt` function (*New*)

Prototype:

```
s8 adl_callSetupExt ( ascii * PhoneNb, u8 Mode, adl_port_e Port );
```

This function sets up a call to a specified phone number.

### 5.17.3 The `adl_callHangup` function (*Unchanged*)

This function calls the `adl_callHangupExt` function on the `ADL_PORT_OPEN_AT_VIRTUAL_BASE` port.

### 5.17.4 The `adl_callHangupExt` function (*New*)

Prototype:

```
s8 adl_callHangupExt ( adl_port_e Port );
```

This function hangs up the phone call.

### 5.17.5 The `adl_callAnswer` function (*Unchanged*)

This function calls the `adl_callAnswerExt` function on the `ADL_PORT_OPEN_AT_VIRTUAL_BASE` port.

### 5.17.6 The `adl_callAnswerExt` function (*New*)

Prototype:

```
s8 adl_callAnswerExt ( adl_port_e Port );
```

This function answers the incoming phone call.

## **5.18 GPRS Service**

### **5.18.1 The `adl_gprsSetup` function (*Unchanged*)**

This function calls the `adl_gprsSetupExt` function on `ADL_PORT_OPEN_AT_VIRTUAL_BASE` port.

### **5.18.2 The `adl_gprsSetupExt` function (*New*)**

Prototype:

```
s8 adl_gprsSetupExt ( u8 Cid, adl_gprsSetupParams_t Params, adl_port_e Port );
```

This function sets up the PDP context activated by its CID with specific parameters.

### **5.18.3 The `adl_gprsAct` function (*Unchanged*)**

This function calls the `adl_gprsActExt` function on `ADL_PORT_OPEN_AT_VIRTUAL_BASE` port.

### **5.18.4 The `adl_gprsActExt` function (*New*)**

Prototype:

```
s8 adl_gprsActExt ( u8 Cid, adl_port_e Port );
```

This function activates the specific PDP context identified by its CID.

### **5.18.5 The `adl_gprsDeact` function (*Unchanged*)**

This function calls the `adl_gprsDeactExt` on `ADL_PORT_OPEN_AT_VIRTUAL_BASE` port.

### **5.18.6 The `adl_gprsDeactExt` function (*New*)**

Prototype:

```
s8 adl_gprsDeactExt ( u8 Cid, adl_port_e Port );
```

This function deactivates the PDP context identified by its CID with specific parameters.

### **5.18.7 The adl\_gprsIsAnIpAddress function (New)**

Prototype:

```
s8 adl_gprsIsAnIpAddress ( ascii *AddressStr );
```

This function checks whether the provided string is a valid IP address.

## 5.19 AT Strings Service

The structure containing the list of the AT standard response string has been modified in the new version. The area in bold gives the modifications

```
typedef enum
{
    ADL_STR_NO_STRING, // Unknown string
    ADL_STR_OK,        // "OK"
    ADL_STR_BUSY,     // "BUSY"
    ADL_STR_NO_ANSWER, // "NO ANSWER"
    ADL_STR_NO_CARRIER, // "NO CARRIER"
    ADL_STR_CONNECT,  // "CONNECT"
    ADL_STR_ERROR,    // "ERROR"
    ADL_STR_CME_ERROR, // "+CME ERROR:"
    ADL_STR_CMS_ERROR, // "+CMS ERROR:"
    ADL_STR_CPIN,     // "+CPIN:"
    ADL_STR_LAST_TERMINAL, // Terminal resp. are before this line
    ADL_STR_RING = ADL_STR_LAST_TERMINAL, // "RING"
    ADL_STR_WIND,     // "+WIND:"
    ADL_STR_CRING,   // "+CRING:"
    ADL_STR_CPINC,   // "+CPINC:"
    ADL_STR_WSTR,    // "+WSTR:"
    ADL_STR_CMEE,    // "+CMEE:"
    ADL_STR_CREG,    // "+CREG:"
    ADL_STR_CGREG,   // "+CGREG:"
    ADL_STR_CRC,     // "+CRC:"
    ADL_STR_CGEREP,  // "+CGEREP:"
    // Last string ID
    ADL_STR_LAST
} adl_strID_e;
```

## 6 New Features in ADL

### 6.1 Application & Data Storage service

This service provides an enhanced large flash storage service, usable to download new data or software elements. This service replaces the old v2 generation Scratch Memory API.

#### 6.1.1 The `adl_adSubscribe` function (*New*)

Prototype :

```
s32 adl_adSubscribe ( u32 CellID, u32 Size );
```

Subscribes to an A&D cell identifier in order to read / write it.

#### 6.1.2 The `adl_adWrite` function (*New*)

Prototype :

```
s32 adl_adWrite ( u32 Handle, u32 Size, void * Data );
```

Writes data in an A&D subscribed cell.

Old interface
<pre>// Writes data s32 sRet = wm_scmWrite ( Size, pData );</pre>
New interface
<pre>// Writes data s32 sRet = adl_adWrite ( ADHdl, Size, pData );</pre>

### 6.1.3 The `adl_adInfo` function (New)

Prototype :

```
s32 adl_adInfo ( u32 Handle, adl_adInfo_t * Info );
```

Gets information from an A&D subscribed cell.

Old interface
<pre>// Reads data s32 sRet = wm_scmRead ( Size, pData );</pre>
New interface
<pre>// Gets information adl_adInfo_t Info;  s32 sRet = adl_adInfo ( ADHdl, &amp;Info );  // Reads data (direct memory access) wm_memcpy ( pData, Info.data, Size );</pre>

### 6.1.4 The `adl_adFinalize` function (New)

Prototype :

```
s32 adl_adFinalise ( u32 Handle );
```

Finalizes a cell; After this, cell is in read-only mode.

Old interface
<pre>// Close Scratch Memory s32 sRet = wm_scmClose();</pre>
New interface
<pre>// Finalize cell s32 sRet = adl_adFinalize ( ADHdl );</pre>

### 6.1.5 The `adl_adInstall` function (New)

Prototype :

```
s32 adl_adInstall ( u32 Handle );
```

Installs the subscribed A&D cell content.

Old interface
<pre>// Install Scratch Memory content s32 sRet = wm_scmInstall();</pre>
New interface
<pre>// Installs cell s32 sRet = adl_adInstall ( ADHdl );</pre>

### 6.1.6 Other A&D APIs

The A&D service also provides these APIs :

- `adl_adDelete` : to delete a subscribed A&D cell.
- `adl_adRecompact` : to free the deleted cells space.
- `adl_adGetState` : to get the A&D service state.
- `adl_adGetCellList` : to get the current A&D cells list.

## **6.2 GPS service**

This service provides APIs to access the Q2501 product GPS data.



### **6.3 AT/FCM IO ports service**

This ADL application can use this service to be informed about the product AT/FCM IO port states.

## **6.4 RTC Service**

This service provides APIs to access the Real Time Clock in the wireless CPU directly

## 7 Upgrading Module with Open AT<sup>®</sup> OS V3.10 applications

### Important Warning:

Once a new 6.55 Open AT<sup>®</sup> FW (or upper) is downloaded on the product, **any existing Open AT<sup>®</sup> V2.10b or older application must firstly be erased**, using the "AT+WOPEN=4" command.

- On 'B' memory WISMO products, existing v2.10b Open AT<sup>®</sup> application will automatically be erased by the download process ;

Existing applications on the module may be checked with the "AT+WOPEN=2" command. Answers may be:

Firmware Version / Open AT <sup>®</sup> OS version	Answer to AT+WOPEN=2
6.55 / 2.10b	+WOPEN: 2,"AT v03.10","AT v02.10b"
6.55 / 3.10	+WOPEN: 2,"AT v03.10","AT v03.10"

In the second case above:

- the "AT+WOPEN=4" command has to be used to delete the existing v2.10b Open AT<sup>®</sup> application **or**
- a new v3.10 Open AT<sup>®</sup> application should be downloaded in order to overwrite the existing one.

## **8 SDK Tools evolutions**

### **8.1 SDK Setup**

The Open AT<sup>®</sup> setup is re-designed in Open AT<sup>®</sup> OS V3.10:

- Already installed components are automatically detected ;
- No more additional setup script to call from the Cygwin command line ;
- No more manually environment variable update.

Please refer to the Getting Started guide to know how the Open AT<sup>®</sup> V3.10 setup runs.

### **8.2 Sample HTML documentation**

To provide more information, and clearer implementation documentation about provided Open AT<sup>®</sup> samples, a new Sample HTML documentation set is available on Open AT<sup>®</sup> V3.10 IDE.

### 8.3 Open AT<sup>®</sup> Settings

A new graphical application is designed to setup the Open AT<sup>®</sup> related environment variables and options.

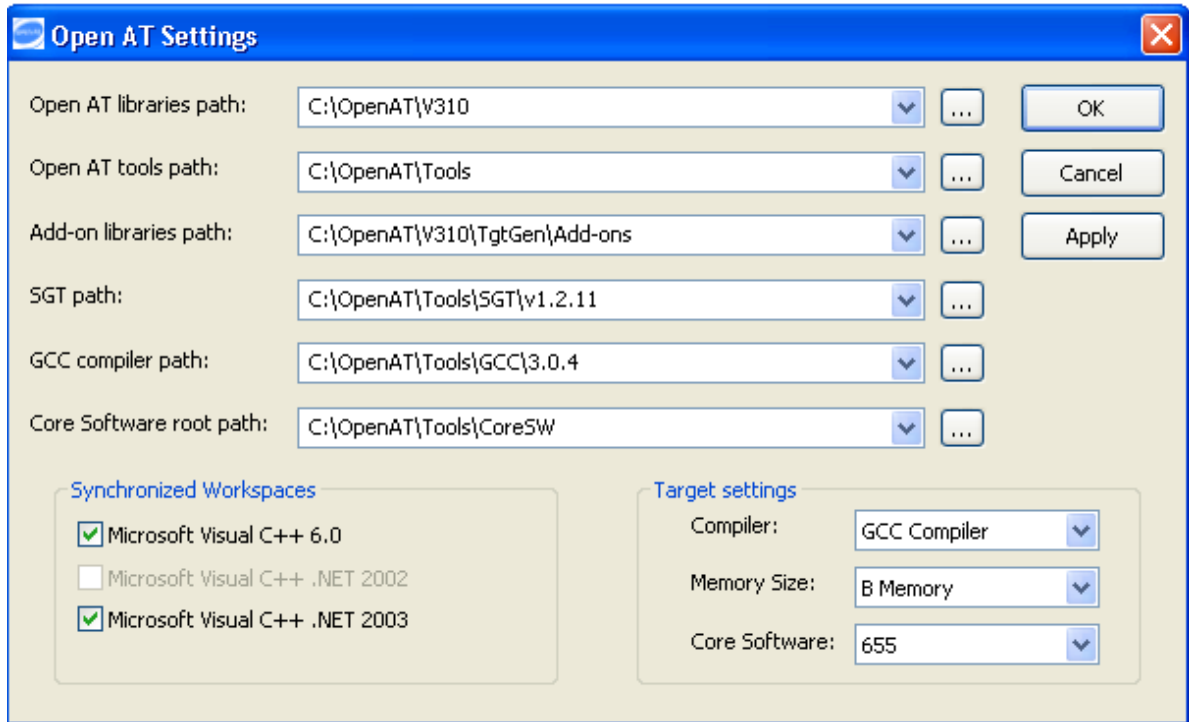


Figure 1: Open AT<sup>®</sup> settings window

Please refer to the Tools Manual to know how the Open AT<sup>®</sup> Settings application runs.

## 8.4 Open AT<sup>®</sup> Project Wizard

The "Wizard" concept of previous Open AT<sup>®</sup> OS versions is extended in Open AT<sup>®</sup> OS V3.10b. A generic Project Wizard application is provided, to create all your Remote & Target modes Open AT<sup>®</sup> projects.

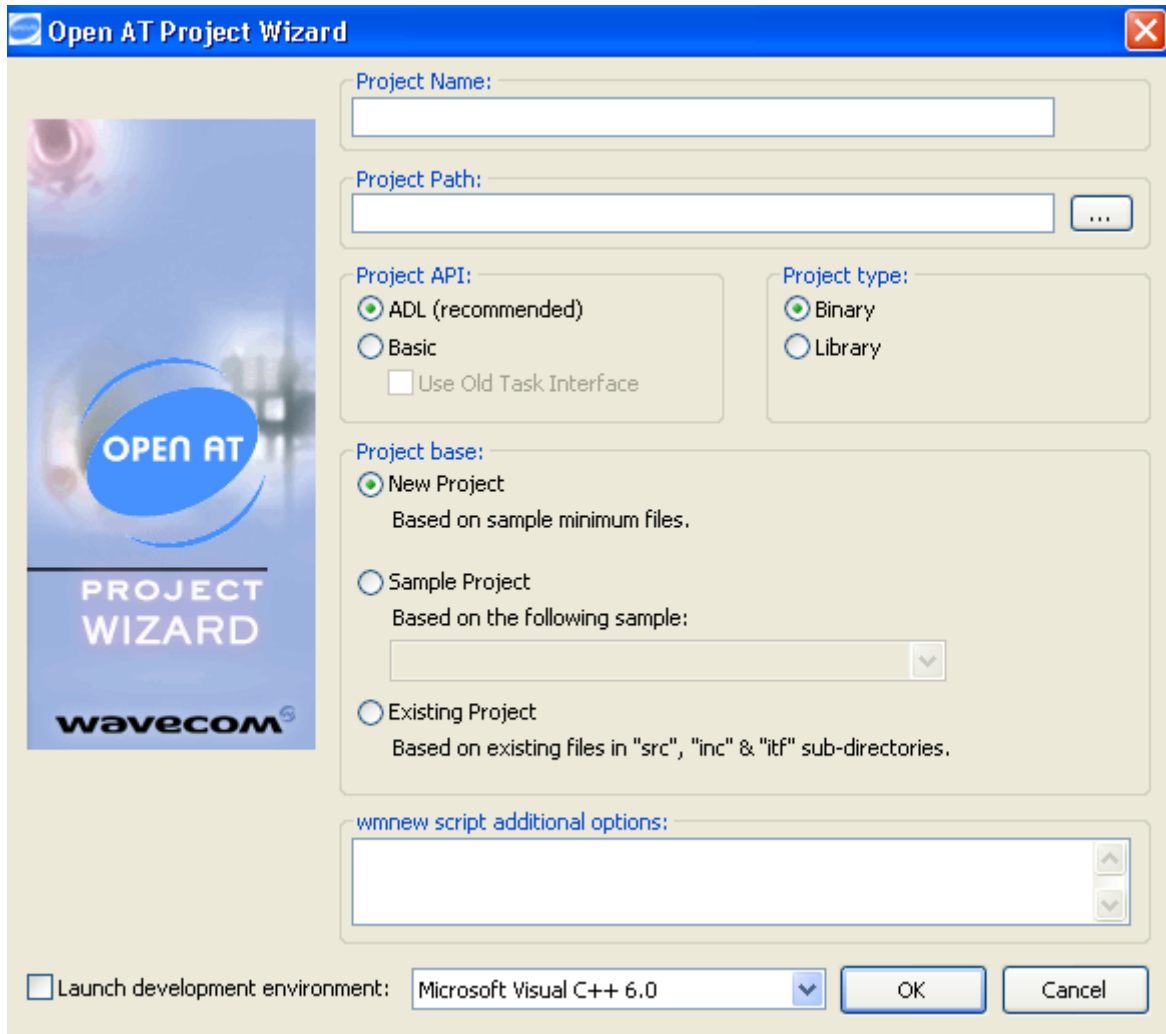


Figure 2: Project wizard window

The Visual C++ integrated wizards still exist, but these ones just start to Generic Wizard.

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The wmnew script still exists (the Project Wizard is in fact a graphical interface which the wmnew script in background), but should not be called anymore from the Cygwin command line.

The compiler & memory settings are moved from wmnew script to wmmake script. It means that the created Open AT<sup>®</sup> V3.10 projects are generic for all environments and compilers. Environment & compiler configuration is set at compilation time.

## **8.5 Extended IDE support**

Supported Integrated Development Environments may be used to build both Remote & Target mode applications (the wmmake script should not be called any more from the Cygwin command line).

The currently supported IDE are:

- Microsoft Visual C++ 6.0 ;
- Microsoft Visual C++ .NET 2002 ;
- Microsoft Visual C++ .NET 2003.

## 8.6 Enhanced Remote Task Environment

The Open AT<sup>®</sup> V3 Remote mode stability is quite better than previous versions one. Limitations due to Real-Time & Compiler behavior differences still exist, but many Remote mode issues were solved in Open AT<sup>®</sup> OS V3.10.

Graphical interface is also modified, to provided easier RTE mode configuration.

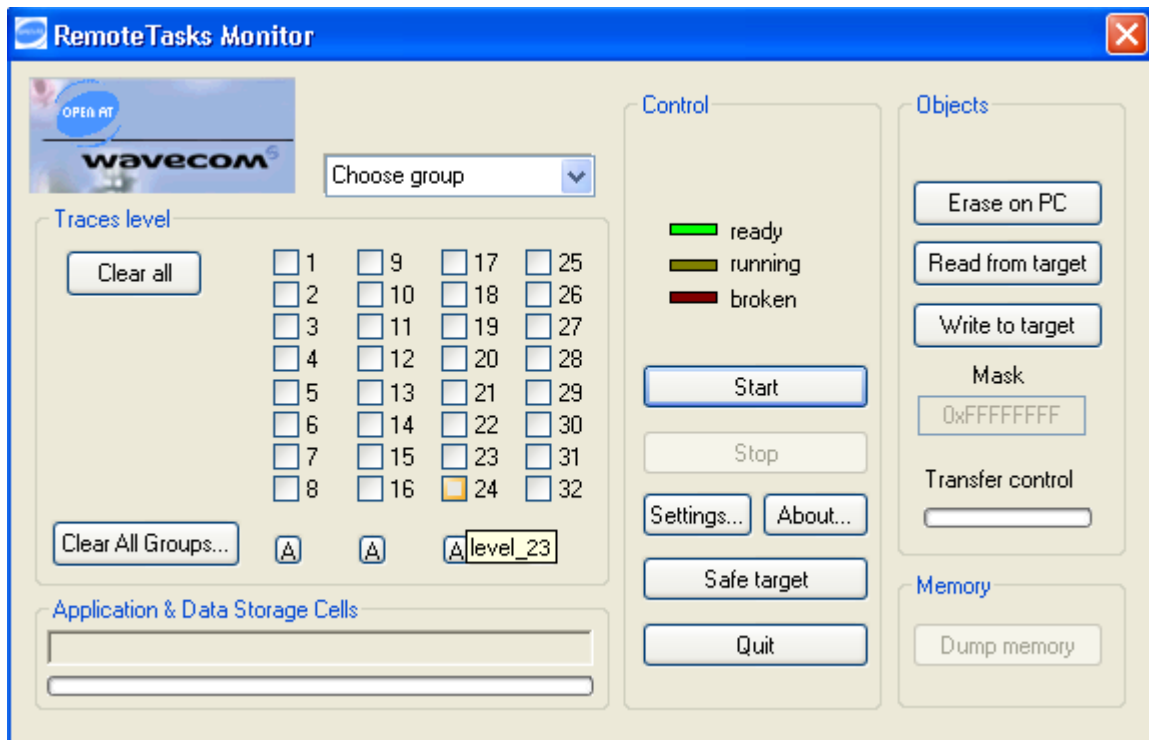


Figure 3: RTE configuration window



## **9 Specificities between v3.0x and v3.1x**

This section lists the new features from the v3.0x and v3.1x version.

### **9.1 Features from v3.01**

#### **9.1.1 No Interface break**

This version does not include any interface break in the Open AT API.

**Important Note:**

In order to run properly an Open AT<sup>®</sup> application using the FCM service, a 650a or higher firmware has to run on the target.

With applications which do not use the FCM service, existing 650 firmware is still compatible with this version.

### **9.2 Features from v3.02**

#### **9.2.1 Open AT<sup>®</sup> API**

WAP services have been removed from the ADL & Basic APIs

### **9.3 Features from v3.03**

#### **9.3.1 Text mode commands**

A new `adl_atCmdSendText ()` function is available since 3.03 API version, and has to be used to handle text mode commands (e.g. AT+CMGW or others). Applications which were using such commands have to be modified.

### **9.4 Features from v3.04**

None

## 9.5 Features from v3.10

### 9.5.1 New IO Ports service

A new ADL Port service is now available to monitor hardware (UART1, UART2) or virtual (MUX 27.010 DLC, Bluetooth,) ports on the module, usable to exchange AT commands & FCM data blocks between the WAVECOM OS and the Open AT<sup>®</sup> OS & external applications.

A new Open AT<sup>®</sup> virtual port has been created, especially to process only AT commands coming from the embedded application (in order not to be disturbed by any command coming from an external port).

### 9.5.2 AT commands / Call / GPRS services updates

These services have been modified in order to handle the extended WAVECOM 6.55 Open AT<sup>®</sup> FW ports capabilities:

- New macros (`adl_atSendResponsePort`, `adl_atSendStdResponsePort` & `adl_atSendStdResponseExtPort`), usable to send responses on a specific port.
- `adl_atCmdCreate` function now returns error codes on specific cases (a bad AT command syntax, or an unknown port); by default, this function also sends AT commands on the new Open AT<sup>®</sup> virtual port (instead of the UART1 on former versions).
- New functions (`adl_callSetupExt`, `adl_callHangupExt` & `adl_callAnswerExt`), usable to execute call service actions on a specific port, instead of the default virtual Open AT<sup>®</sup> one.
- New functions (`adl_gprsSetupExt`, `adl_gprsActExt` & `adl_gprsDeactExt`), usable to execute GPRS service actions on a specific port, instead of the default virtual Open AT<sup>®</sup> one.

### 9.5.3 Extended A&D storage capabilities

No A&D service API update was performed, but the A&D storage size is now configurable through the `AT+WOPEN=6` command mode. Please refer to the AT commands interface guide for more information.

### 9.5.4 New RTC service

A new RTC service is now available to provide Open AT<sup>®</sup> applications with Real Time Clock synchronous information. Please refer to the ADL Development Guide for more information.

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### **9.5.5 Extended Errors management service**

The Errors management service has been updated to provide Open AT<sup>®</sup> applications with the capability to retrieve errors stored in the module's memory (called back-traces), in order to read these ones on a remote computer.

### **9.5.6 New DTL & GRL add-on libraries**

Two new add-on libraries are now provided on the SDK:

- DTL (Data Transfer Layer) which provides an IP link configuration layer (through an API & AT commands set), and a generic data transfer layer API, usable to send/receive a data buffer to/from a remote server, through an FTP, e-mail or SMS bearer.
- GRL (Generic Reporting Layer) which provides a generic report storage API, and a configurable report sending mechanism (scheduler or size limit) in order to regularly send the stored reports to a remote server.

### **9.5.7 Text commands handling**

A new `ad1_atCmdSendText` function is available since 3.10 API versions, and has to be used to handle text mode commands (e.g. AT+CMGW or others). Applications which were using such commands have to be modified.

## **9.6 Features from v3.12**

### **9.6.1 Handle 32/16 memories**

This version handles memories 32/4 type B and 32/16 type F; only samples for 32/4 memory are provided in the SDK.

### **9.6.2 9.7.2 IP plugin WIP**

Plug-in WIP is a new plug-in to handle UDP and TCP socket. In this beta version All functionality are not available, and the behaviour is not guaranteed.

### **9.6.3 Cmux Tool**

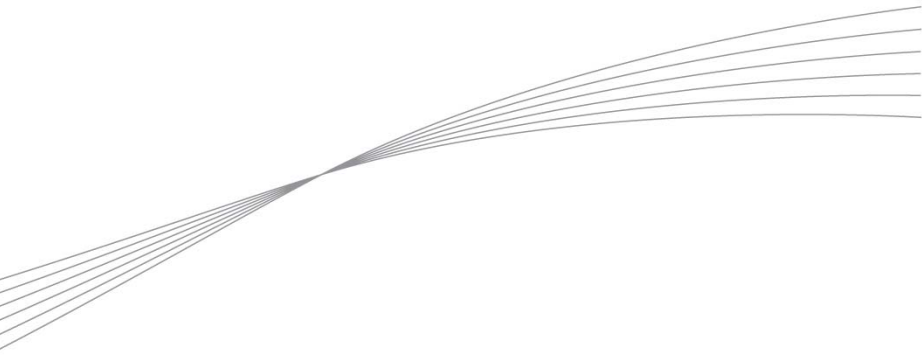
The last driver for Cmux tool is now available in the Cdrom, and can be installed from the new folder Cmux Tools.

#### **9.6.4 I2C Hard**

I2C Hard can be now handled with Open AT<sup>®</sup> OS.

#### **9.6.5 WTP Plug-in**

WTP Plug-in has been removed.



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